Subproblem pseudomarginal reversible jump MCMC in probabilistic programming languages

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1. Address and traces in Gen

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Cusumano-Towner, Marco. Gen: A High-Level Programming Platform for Probabilistic Inf

3. Use approx. samplers in the auxiliary probabilistic



(Sampling from exact conditionals)

(c) This work: Approximately conditionally sample new (+ optionally, some old) choices within a structure change



"<u>Subproblem</u>" = Any previously nonexistent addresses, and any addressed in the (optional) "shared subproblem"

Generalizes "subproblem" MCMC (Mansinghka et al., 2014): (1) Can use approximate instead of exact samplers (2) Applies generally to structure-changing moves

Marco Cusumano-Towner

MIT Probabilistic Computing Project

			2. Invo
choice es	Addresses sampled if z = true	Addresses sampled if z = false	A custo
	Z	Z	
a 2	a1 a2 a y1 y2	a1 a2 a y1 y2	Auxiliary @gen fund if !tra # swi {:dof end end
			Trace tr
	Observed data $(y1 = 1.0, y2 = 1.4)$	$\begin{array}{c} 2 \\ 1 \\ 0 \\ 1 \\ 1 \\ 1 \end{array} $	@transfor if @rea # cur @writ m1 =
Posterior samples (traces)			m2 = (m, d @writ
(z = t) $(z = t)$ $(z = f)$ $(z = f)$ 2 1 0 1	rue, $a1 = 1.22, a2 = 1.40$ rue, $a1 = 1.27, a2 = 1.53$ alse, $a = 1.09,$ alse, $a = 1.23,$ alse, $a = 1.13,$ $21 \xrightarrow{1}_{0} \xrightarrow{1}_{1} \xrightarrow{2}_{1} \xrightarrow{1}_{0} \xrightarrow{1}_{1} \xrightarrow{1}_{2} \xrightarrow{1}_{1} \xrightarrow{1}_{0} \xrightarrow{1}_{1} \xrightarrow{1}_{2} \xrightarrow{1}_{1} \xrightarrow{1}_{0} $	9, $y1 = 1.0, y2 = 1.4$) 9, $y1 = 1.0, y2 = 1.4$) 1, $y1 = 1.0, y2 = 1.4$)	@writ @writ else # cur @writ m = @ dof = (m1, @writ @writ end end Cusumano-To "Automating
ference. P	hD thesis. MIT 2020. <u>Link to PC</u>	<u>DF</u>	arXiv preprint
c progi	ram to infer values	s of new addresses	4. App
Igorithm 1 So procedure so $m \sim q(\cdot; z)$ $u', \theta'_{(I_{z'} \setminus I_{z})}$ $\theta'_{I_{z'}} \leftarrow (\theta)$ $\hat{p}(y \theta_{(I_{z} \cap I_{z})})$ $u \sim r(\cdot; m)$ $\hat{p}(y \theta_{(I_{z} \cap I_{z})})$ $a \leftarrow \frac{q(m)}{q(m)}$ return Ac end procedure M procedure M procedure A $\psi \sim Unifo$ if $h \to c \in a$	ubproblem pseudomarginal reversible ju: PRJ-KERNEL(z, θ_{I_z})) \sim Sample a move) $\cup S_m \sim q(\cdot; m, z', \theta_{(I_z \cap I_{z'}) \setminus S_m}, y)$ $P(I_z \cap I_{z'}) \setminus S_m, \theta'_{(I_{z'} \setminus I_z) \cup S_m}$) \sim Form completed $P(I_z \cap I_{z'}) \setminus S_m, \theta'_{(I_{z'} \setminus I_z) \cup S_m}$) \sim Run metators $P(I_z \cap I_{z'}) \setminus S_m, y, \theta_{(I_z \setminus I_{z'}) \cup S_m}) \sim$ Run metators $P(I_z \cap I_{z'}) \setminus S_m, y, \theta_{(I_z \setminus I_{z'}) \cup S_m}) \sim$ Run metators $P(I_z \cap I_{z'}) \setminus S_m, y, \theta_{(I_z \setminus I_{z'}) \cup S_m}) \sim$ Run metators $P(I_z \cap I_{z'}) \setminus S_m, y, \theta_{(I_z \cap I_{z'}) \setminus S_m}); z')$ $P(Z) \hat{p}(y \theta_{(I_z \cap I_{z'}) \setminus S_m}); z')$ $P(Z) \hat{p}(y \theta_{(I_z \cap I_{z'}) \setminus S_m}); z)$ CCEPT-REJECT($a, (z, \theta_{I_z}), (z', \theta_{I_{z'}}) \sim$ A tree $P(I_z; z') p(y; z', \theta'_{I_z}) P(u'; m, z', \theta'_{(I_z \cap I_{z'}) \setminus S_m}); z')$ $P(U', \theta'_{(I_{z'} \setminus I_z) \cup S_m}; m, z', \theta_{(I_z \cap I_{z'}) \setminus S_m}); z')$ tree CCEPT-REJECT(a, x, x') $P(I_z) P(I_z) P(I_$	mp (SPRJ) MCMC kernel template type <i>m</i> which moves to new structure z' > Run sampler on forward subproblem te set of parameter values for structure z' > Forward marginal likelihood estimate -inference for reverse subproblem sampler > Reverse marginal likelihood estimate > Compute acceptance probability ccept or reject proposed move to $(z', \theta'_{I_{z'}})$ $(y, \theta'_{(I_{z'} \setminus I_z) \cup S_m})$ (y, y)	end
if $w \le a$ end procedu	then return x' else return x ire		5. App
gorithm 2 SP	PRJ kernel using annealed importance sar	npling for subproblem inference (AIS-SPRJ)	Т
procedure SPRJ-KERNEL-AIS (z, θ_{I_z}) $m \sim q(\cdot; z)$ > Sample a move type <i>m</i> which moves to new structure <i>z'</i>			71
$ \begin{array}{c} \left(\theta_{(I_{z'} \setminus I_z) \cup S}' \\ \hat{p}(y \theta_{(I_z \cap I_{z'})} \\ q(m; \end{array} \right) $	$ \hat{p}(y \theta_{(I_z \cap I_{z'}) \setminus S_m)}; z')) \sim \operatorname{AIS}(m, z', \theta_{(I_z \cap I_{z'}) \setminus S_m)}; z) \sim \operatorname{R-AIS}(m, z, \theta_{(I_z \cap I_{z'}) \setminus S_m}, y, \theta_{(I_z \cap I_{z'}) \setminus S_m)}; z') $	$(I_{z'}) \setminus S_m, y) $ \triangleright AIS on forward subproblem $(I_{z'}) \cup S_m) $ \triangleright Reverse AIS on rev. subproblem	\sim_1

Compute acceptance probability $\overline{q(m;z')p(z)\hat{p}(y|\theta_{(I_z\cap I_{z'})\setminus S_m)};z)}$ **return** ACCEPT-REJECT $(a, (z, \theta_{I_z}), (z', \theta_{I_{z'}}))$ ▷ Accept or reject proposed move to $(z', \theta'_{I_{i}})$ end procedure

Related work: Georgios Karagiannis and Christophe Andrieu. 2013. Annealed importance sampling reversible jump MCMC algorithms. Journal of Computational and Graphical Statistics 22, 3 (2013), 623–648. Vikash K. Mansinghka

olutive MCMC and custom reversible jump MCMC in Gen



; Involutive MCMC using Probabilistic and Differentiable Programming.' : arXiv:2007.09871 (2020). <u>Link to PDF</u>

proximates standard Gibbs sampling when there is no structure change

A model with fixed structure

- gen function model(noise::Float64) x = @trace(normal(0, 1), :x)
- z = @trace(normal(0, 1), :z)
- = @trace(normal(x + z, noise), :y)

onditional distribution on x, z given y



Iterates from two different AIS-SPRJ kernels



Cycle of two AIS-SPRJ kernels with subproblems {x} and {z}

lication: Inferring geometric scene graph structure (tree-based pose parametrization)

Tree of coordinate frames in a scene



 z_3

Three possible trees for a scene with two objects

• Root node is the world coordinate frame

• Other nodes are objects' coordinate frames (poses)

• Edges from one object to another indicate sliding (3) degree-of-freedom) contact between objects

• Edges from root to to object indicate the object has a full 6 degree-of-freedom pose





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An AIS-SPRJ kernel with subproblem {x,z}

MCMC move on the tree (prune and regraft)

Use AIS to infer new continuous pose parameters during each move

