

Introduction

- *Markov chain Monte Carlo* (MCMC) algorithms are workhorses for approximate inference in probabilistic programs.
- MCMC methods approximate the posterior via the simulation of a Markov chain whose stationary distribution is the posterior distribution.
- Existing probabilistic programming systems cannot reason about the error introduced by simulating Markov chains for a finite number of steps — specially under composition of multiple approximate programs (or nested programs).

Contributions

1. Introduced a **stat** construct, that allows programmers to represent stationary distribution associated with a specified Markov chain, to the language proposed by Staton et al, 2016 and showed that the language constructs for conditioning and normalization are eliminable.
2. Under the assumptions of *uniform ergodicity*, gave quantitative error bounds for simulation based approximate implementation of **stat**.

Probabilistic programming language with the stationary construct

We extend the first order probabilistic language with probabilistic constructs **sample**, **score**, and **norm**. First, we briefly review the semantics of probabilistic terms and introduce the semantics of the **stat** terms.

Sequencing, case and sampling terms:

$$\llbracket \mathbf{sample}(t) \rrbracket_{\gamma, A} \stackrel{\text{def}}{=} \llbracket t \rrbracket_{\gamma, A}, \llbracket \mathbf{let } x = t_1 \mathbf{ in } t_2 \rrbracket_{\gamma, A} \stackrel{\text{def}}{=} \int_{[\mathbb{A}]} \llbracket t_2 \rrbracket_{\gamma, x, A} \llbracket t_1 \rrbracket_{\gamma, dx}$$

$$\llbracket \mathbf{case } a \mathbf{ of } \{(i, x) \Rightarrow t_i\}_{i \in I} \rrbracket_{\gamma, v} \stackrel{\text{def}}{=} \llbracket t_i \rrbracket_{\gamma, v} \quad \text{if } \llbracket a \rrbracket_{\gamma} = (i, v)$$

Normalization and soft conditioning terms:

$$\llbracket \mathbf{score}(a) \rrbracket_{\gamma, A} \stackrel{\text{def}}{=} \begin{cases} |\llbracket t \rrbracket_{\gamma}| & \text{if } A = \{()\} \\ 0 & \text{otherwise} \end{cases}$$

$$\llbracket \mathbf{norm}(t) \rrbracket_{\gamma, A} = \begin{cases} \frac{\llbracket t \rrbracket_{\gamma, \{u | (0, u) \in A\}}}{\llbracket t \rrbracket_{\gamma, [\mathbb{A}]}} & \text{if } \llbracket t \rrbracket_{\gamma, [\mathbb{A}]} \in (0, \infty) \\ \delta_{(1, ())}(A) & \text{otherwise} \end{cases}$$

Stationary terms:

Given an initial distribution t_0 and a probability transition kernel $\lambda x.t_1$:

$$\llbracket \mathbf{stat}(t_0, \lambda x.t_1) \rrbracket_{\gamma, A} = \begin{cases} \mu(\{u : (0, u) \in A\}) & \text{if } \exists! \mu \in \mathcal{M}([\mathbb{A}]) : \int_{[\mathbb{A}]} \llbracket t_1 \rrbracket^{(n)}(x, \cdot) \rightarrow_n \mu \\ \text{for } x \text{ a.e. } \llbracket t_0 \rrbracket_{\gamma} \\ \delta_{(1, ())}(A) & \text{otherwise} \end{cases}$$

Theorem (Soft conditioning and normalization terms are eliminable from the language)

Call the programming language defined before \mathcal{L} . Let \mathcal{L}' be a programming language such that:

- the set of \mathcal{L}' -phrases is the full subset of \mathcal{L} -phrases that do not contain **norm** and **score**;
- the set of \mathcal{L}' -programs is the full subset of \mathcal{L} -programs that do not contain **norm** and **score**;
- the semantics of \mathcal{L}' is a restriction of \mathcal{L} 's semantics.

Then, every program that can be represented in \mathcal{L} can also be represented in \mathcal{L}' .

Approximate compilation of probabilistic programs

Problem (Failure of arbitrary approximate implementation.)

For some term $\Gamma \frac{}{p1} \mathbf{stat}(t_0, \lambda x.t_1) : \mathbb{A} + 1$ if we know that $\llbracket t_1 \rrbracket_{\gamma, x}$ is an ergodic kernel that has a unique stationary distribution, it is possible to construct an approximate Markov transition kernel $\lambda x.t'_1$ such that

$$\exists \delta \in (0, 1) \forall \gamma, x. \left\| \llbracket t_1 \rrbracket_{\gamma, x} - \llbracket t'_1 \rrbracket_{\gamma, x} \right\|_{\text{tv}} \leq \delta,$$

but

$$\left\| \llbracket \mathbf{stat}(t_0, \lambda x.t_1) \rrbracket_{\gamma} - \llbracket \mathbf{stat}(t_0, \lambda x.t'_1) \rrbracket_{\gamma} \right\|_{\text{tv}} = 1.$$

Such an example is given in Proposition 1 of Roberts et al. (1998).

This tells us that **stat** construct is not continuous and we need to be careful how to approximate **stat**. Now we look at what goes on under the hood of a compiler:

Example compilation:

$$\text{BetaPost}(N_F, N_P) := \mathbf{norm} \left(\begin{array}{l} \mathbf{let } p = \mathbf{Beta}(1, 1) \mathbf{ in} \\ \mathbf{score} (p^{N_F}(1-p)^{N_P}); \\ \mathbf{return}(p) \end{array} \right)$$

Compiling away the **norm** and **score** terms:

$$\text{MHkern}(Q, p, N_F, N_P) := \mathbf{let } p' = Q \mathbf{ in}$$

$$\mathbf{case } \mathbf{sample}(\text{Bern}(\min \left\{ 1, \frac{p'^{N_F}(1-p')^{N_P}}{p^{N_F}(1-p)^{N_P}} \right\})) \mathbf{ of}$$

$$\begin{array}{l} (0, T) \Rightarrow \mathbf{return}(p') \\ | (1, F) \Rightarrow \mathbf{return}(p) \end{array}$$

$$\text{BetaPost}(N_F, N_P) \rightsquigarrow \mathbf{stat}(\mathbf{Beta}(1, 1), \lambda p. \text{MHkern}(\mathbf{Beta}(1, 1), p, N_F, N_P))$$

Approximate implementation of the **stat** term by iterating:

$$\text{ApproxBetaPost}(N_F, N_P, k) := \mathbf{let } p = \mathbf{Beta}(1, 1) \mathbf{ in}$$

$$\left. \begin{array}{l} \mathbf{let } p = \text{MHkern}(\mathbf{Beta}(1, 1), p, N_F, N_P) \mathbf{ in} \\ \mathbf{let } p = \text{MHkern}(\mathbf{Beta}(1, 1), p, N_F, N_P) \mathbf{ in} \\ \vdots \\ \mathbf{let } p = \text{MHkern}(\mathbf{Beta}(1, 1), p, N_F, N_P); \mathbf{return}(p) \end{array} \right\} (k \text{ steps})$$

Theorem (Quantitative error bound for proposed approximations)

Let P be a probabilistic program in the language $\mathcal{L}_{\mathbf{stat}}$. Let $\{\mathbf{stat}(t_{0i}, \lambda x.t_{1i})\}_{i \in I}$ be the set of all stationary terms in the program $\emptyset \frac{}{p1} P : \mathbb{B}$ such that for all γ , there exist constants $\{C_i\}$ and $\{\rho_i\}$ such that the Markov chain with the initial distribution $\llbracket t_{0i} \rrbracket_{\gamma}$ and Markov transition kernel $\llbracket t_{1i} \rrbracket_{\gamma}$ is uniformly ergodic with constants C_i, ρ_i . Let P' be a program where for all $i \in I$ and $N_i \in \mathbb{N}$, $\mathbf{stat}(t_{0i}, \lambda x.t_{1i})$ is replaced by $\phi(\mathbf{stat}(t_{0i}, \lambda x.t_{1i}), N_i)$. Then, there exist constants $\{C'_i\}_{i \in I}$ such that

$$\left\| \llbracket P \rrbracket_{\gamma} - \llbracket P' \rrbracket_{\gamma} \right\|_{\text{tv}} \leq \sum_{i \in I} C'_i \rho_i^{N_i}.$$